A. Y : 2024/2025

University of Tlemcen Faculty of Sciences Department of Mathematics

1ST YEAR LMD-MI

ELECTRICITY COURSE

Chapter II: Gauss's theorem

Prepared by : Ms Hadjou Belaid Zakia



Sommaire

1. Introduction	3
2. Definitions	3
3. Electric field flow through a closed surface	3
4. Gauss theorem	4
5. Examples of GT applications	5
5.1. Case of an infinite wire	5
5.2. Case of an infinite cylinder	7
5.3. Case of an sphere	10
5.4. Case of an infinite plan	13

1. Introduction

Gauss's law is a mathematical model that can be used to obtain the electric fields of certain charge distributions with a high degree of symmetry, such as cylinders, spheres and infinite wires.

It is therefore a specialized method, but it is very useful for this class of problems to which it can be applied. At this stage, Gauss's law will help us to better understand the shapes of electric fields due to continuous charge distributions.

2. Definitions

A- Surface vector: The surface vector \overrightarrow{ds} is a vector carried by the unit vector normal to the surface.

B- Flux of a vector field: The elementary flux $d\Phi$ is,

$$d\emptyset = \vec{E}.\vec{ds} \Rightarrow \emptyset = \iint \vec{E}.\vec{ds} = \iint \vec{E}.ds.\vec{N}$$



With $\overrightarrow{ds} = ds. \overrightarrow{N}$

The unit of flow is the Weber (Wb).

3. Electric field flow through a closed surface

Let S be an arbitrary closed surface and q be the charge enclosed within the surface S. The elementary electric field flux created by the charge q across the closed surface S is given by:

$$d\phi = \vec{E} \cdot \vec{ds} = E \cdot ds \cdot \cos \alpha$$

 α : the angle between \vec{E} and \vec{N} (\vec{ds})

The electric field $\vec{E} = \frac{kq}{r^2}\vec{u}$ and $d\emptyset = \frac{kq}{r^2}\vec{u} \cdot \vec{ds} = kq\frac{\vec{u} \cdot \vec{ds}}{r^2}$

$$\vec{u} \cdot \vec{ds} = ds |\vec{u}| \cos \alpha$$



The electric field will be :

 $\vec{E} = \frac{kq}{r^2}\vec{u}$ and $\phi = \bigoplus \frac{kq}{r^2}\vec{u} \cdot \vec{ds} = \oiint kq \frac{ds.cos\alpha}{r^2}$

with $\frac{ds. cos\alpha}{r^2} = d\Omega = solid angle$

Note: The unit of the solid angle is the steradian.

Since the area of a sphere of radius *R* is $S = 4\pi R^2$, we deduce that the largest measurable solid angle, which corresponds to an object covering the entire sphere, is 4π steradians.

 $\Omega = 4\pi$ = the solid angle to see all of space

So
$$\emptyset = \frac{q}{4\pi\varepsilon_0} \cdot 4\pi = \frac{q}{\varepsilon_0}$$

In the case of several point charges, the flux is written as:

$$\phi = \oint \vec{E} \cdot \vec{ds} = \frac{\sum Q_{\text{int}}}{\varepsilon_0}$$

4. Gauss Theorem

a- Statement of Gauss Theorem

« The flux inside a closed surface called a Gauss surface is equal to the sum of the net charges Q_{int} inside this surface divided by the dielectric permittivity in vacuum ϵ_0 »

$$\emptyset = \oint \vec{E} \cdot \vec{ds} = \frac{\sum \mathbf{Q}_{\text{int}}}{\mathbf{\varepsilon}_0}$$

b. The steps involved in applying Gauss's theorem

- Choosing a coordinate system
- Study the invariance of the system
- Study symmetry
- Choice of Gaussian surface; the table shows the different cases where a cylinder is chosen as the SG and the cases where a sphere is chosen as the SG:

	Possible cases		Possible cases		Possible cases		Possible cases			
GS is a	An	infinite	An	infinite	А	surface	or	Two	or	more
cylinder	wire		plane		volume			cylinders		
					charged					
					cyl	inder				
GS is a sphere	A sur	face- or	Two o	or more						
	volume	e-	spheres	8						
	charge	d sphere								

c. GT for different continuous charge distribution :

- Linear distribution (dq= λ dl) $\phi = \oint \vec{E} \cdot \vec{ds} = \frac{\int \lambda dl}{\varepsilon_0}$
- Surface distribution (dq= σ ds) $\emptyset = \oiint \vec{E} \cdot \vec{ds} = \frac{\int \sigma ds}{\varepsilon_0}$
- Volume distribution (dq= ρdv) $\phi = \bigoplus \vec{E} \cdot \vec{ds} = \frac{\int \rho dv}{\varepsilon_0}$

5. Application examples

5.1. Case of an infinite wire

- Choice of coordinate system:

If we zoom in on the wire, we'll have a cylinder with an infinitely small radius, so we use cylindrical coordinates.



Study of invariance

-

We study invariance with respect to ρ , θ and z (cylindrical coordinates).

• If we change the angle θ , M rotates around the wire, but the electric field does not change.

• If we change z, M translates along (Oz) and since the wire is infinite, we still have the same wire, so \vec{E} remains invariant remains invariant.

• If we change ρ , M can move away from or towards the wire, so \vec{E} does not remain the same. So \vec{E} depends only on ρ .



Study of symmetry

In this case, we have two planes of symmetry:

1. The plane intersecting the infinite wire horizontally $(\overrightarrow{u_{\rho}}, \overrightarrow{u_{\theta}})$





So the axis of symmetry is the intersection of the

two planes, this is the axis following $\overrightarrow{u_{\rho}}$ so the electric field is following $\overrightarrow{u_{\rho}}$.

- Choice of Gauss surface

The Gaussian surface is a cylinder of radius r and and height h. Because of symmetry, the field follows the radius ρ , so we say the field is said to be "radial" and constant in the Gaussian surface (\vec{E} depends only on ρ).

According to Gauss's Theorem: $\emptyset = \iint \vec{E} \cdot \vec{ds} = \frac{\sum Q_{int}}{\varepsilon_0}$ $\emptyset = \iint \vec{E} \cdot \vec{ds} = \iint \vec{E} \cdot \vec{ds}_{base1} + \iint \vec{E} \cdot \vec{ds_{lat}} + \iint \vec{E} \cdot \vec{ds}_{base2}$ $\vec{E} \perp \vec{ds}_{base} \Rightarrow \iint \vec{E} \cdot \vec{ds_{lat}} = 0$ $\vec{E} \parallel \vec{ds_{lat}}$ so : $\emptyset = \iint \vec{E} \cdot \vec{ds_{lat}} = \iint E \cdot ds_{lat} = E \cdot \int ds_{lat} = E \cdot S_{lat}$



Ms Hadjou Bélaid Z

so $\emptyset = E \ 2\pi rh$

Let's find Q_{int}, the elementary charge is : $dq = \lambda dl \Rightarrow Q = \lambda \int_0^h dl = \lambda h$

$$E2\pi rh = \frac{\lambda h}{\varepsilon_0} \Rightarrow E = \frac{\lambda}{2\pi r\varepsilon_0}$$

5.1. Case of an infinite cylinder

- Choice of coordinate system

Since we're studying a cylinder, we use cylindrical coordinates.

- Study of invariance

It's the same as the wire. The electric field does not change by varying θ and z, however, \vec{E} depends on ρ .

- Study of symmetry

In this case, too, we have two planes of symmetry:

The plane intersecting the infinite wire horizontally $(\overrightarrow{u_{\rho}}, \overrightarrow{u_{\theta}})$ and

The plane intersecting the infinite wire vertically $(\overrightarrow{u_{\rho}}, \overrightarrow{u_z})$

So the axis of symmetry is the intersection of the two planes

It's the axis along $\overrightarrow{u_{\rho}}$ so the electric field is along $\overrightarrow{u_{\rho}}$.

- Choice of Gauss surface

The Gaussian surface is a cylinder of radius r and height h.

Because of symmetry, the radial field is constant in the Gaussian surface

According to Gauss's Theorem: $\emptyset = \iint \vec{E} \cdot \vec{ds} = \frac{\sum Q_{int}}{\varepsilon_0}$

 $\vec{E} \parallel \vec{ds_{lat}}$ so : $\emptyset = \iint \vec{E} \cdot \vec{ds_{lat}} = \iint E \cdot ds_{lat} = E \cdot \int ds_{lat} = E \cdot S_{lat}$

ce.
$$ds_{base sup}$$

 $ds_{base tef}$





Then $\emptyset = E 2\pi r \mathbf{h} = \mathbf{Q}_{int}/\varepsilon_0$



The cylinder can be either surface or volume charged.

Important note:

The choice of Gaussian surface for a cylinder charged either on the surface or in volume, or two cylinders (one charged in volume and the other charged on the surface, or both charged on the surface...) is always a cylinder of radius r and height h. The flux calculation will be the same, only the Q_{int} charge will vary according to the given distribution.

a- For a surface-charded cylinder

- The electric field

We have tos cases ;

<u>**1**st case</u> r < R we take the Gauss surface inside the charged cylinder to calculate the internal field. Then, in a surface distribution, we have :

$$Q_{int} = 0 \Longrightarrow E_1 = E_{ins} = 0$$

<u> 2^{nd} case $r \ge R$ </u> we take the Gauss surface outside the charged cylinder to calculate the field outside.

$$dq = \sigma ds \Rightarrow Q_{int} = \sigma S = \sigma 2\pi Rh$$

So $E_2 2\pi rh = \frac{\sigma 2\pi Rh}{\varepsilon_0} \Rightarrow E_2 = E_{out} = \frac{\sigma R}{\varepsilon_0 r}$

- The potentiel

$$\vec{E} = -\vec{grad}V$$
 with $E = E(r) \Longrightarrow E = -\frac{dV}{dr}$ so $V = -\int E.dr$

<u> $1^{\text{st}} \operatorname{case} r < R$ we have $E_1 = 0 \Longrightarrow V_1 = C_1$ </u>

2^{nd} case $r \ge R$

$$E_2 = \frac{\rho R}{\varepsilon_0} \frac{1}{r} \Longrightarrow V_2 = -\frac{\sigma R}{\varepsilon_0} \int \frac{1}{r} dr = -\frac{\sigma R}{\varepsilon_0} lnr + C_2$$

Note: In the case of a cylinder, the constants C_1 and C_2 cannot be calculated because the potential at infinity is non-zero.



b. Volume-charged cylinder

We have tow cases.

-

The electric field

<u>**1**</u>st <u>case</u> r < R we take the Gauss surface inside the charged cylinder to calculate the internal field. Then, in a volume distribution dq= ρ dV, we have :

$$Q_{int} = \iiint \rho dv = \rho \int_0^r 2\pi h r dr = \rho \pi h r^2 \Rightarrow E 2\pi r h = \frac{\rho \pi h r^2}{\varepsilon_0}$$

Because $V = \pi h r^2 \Rightarrow dV = 2\pi h r dr$

$$\implies E_1 = E_{ins} = \frac{\rho}{2\varepsilon_0}r$$

2^{nd} case $r \ge R$

we take the Gauss surface outside the loaded cylinder to calculate $E_2 = E_{ins}$, so we integrate between 0 and R (because Q_{int} lies on the cylinder of radius R).

$$Q_{int} = \iiint \rho dv = \rho \int_0^R 2\pi h r dr = \rho \pi h R^2 \Rightarrow E 2\pi r h = \frac{\rho \pi h R^2}{\varepsilon_0}$$
$$\implies E_2 = \frac{\rho R^2}{2\varepsilon_0} \frac{1}{r}$$

- The potentiel

$$\overrightarrow{E} = -\overrightarrow{grad} V$$
 with $E = E(r)$

 $\Rightarrow E = -\frac{dV}{dr}$ so $V = -\int E dr$ (this calculation is valid for any cylinder).

$$V_1 = -\int E_1 dr \Longrightarrow V_1 = \frac{\rho}{2\varepsilon_0} \int r dr = -\frac{\rho}{4\varepsilon_0} r^2 + C_1$$

$$V_2 = -\int E_2 \, dr = -\frac{\rho R^2}{2\varepsilon_0} \int \frac{1}{r} \, dr = -\frac{\rho R^2}{2\varepsilon_0} \ln r + C_2$$



5.3. Case of a sphere

- Choice of coordinate system

Since we're studying a cylinder, we use spherical coordinates.

- Study of invariance

If we change the angle θ or the angle φ , the electric field \vec{E}

does not change, but by varying r the electric field \vec{E} varies \vec{E} .

- Study of symmetry

We have two planes of symmetry:

The plane intersecting the infinite wire horizontally $(\vec{u_r}, \vec{u_{\theta}})$ and the plane intersecting the infinite wire vertically $(\vec{u_r}, \vec{u_{\varphi}})$.

So the axis of symmetry is the intersection of the two planes,

This is the axis along $\overrightarrow{u_r}$ so the electric field is along $\overrightarrow{u_r}$

The field is then said to be radial

- Choosing the Gaussian surface

The Gaussian surface is a sphere with center O and radius r. Due to symmetry, the field is radial and constant in the Gaussian surface.

$$\phi = \oint \vec{E} \cdot \vec{ds} = \frac{\sum Q_{int}}{\varepsilon_0}$$

$$\overrightarrow{E}$$
 // \overrightarrow{ds} :

So: $\oiint \vec{E} \cdot \vec{ds} = \iint E \cdot ds = E \iint ds = E \cdot S = E 4\pi r^2 \Rightarrow E 4\pi r^2 = \frac{\sum Q_{int}}{\varepsilon_0}$

Important note:

The choice of Gaussian surface for a sphere charged either on the surface or in volume, or two spheres (one charged in volume and the other charged on the surface, or both charged on the surface...) is always a sphere of radius r and center O. And the flux calculation will be the same, only the Q_{int} charge will vary according to the distribution.







a- Surface-charged sphere

The electrostatic field E(r) at any point in space.

We have 2 cases :

-

1st case r<R

The Gaussian surface is inside the sphere to calculate $E_1 == E_{int}$ then

$$Q_{int} = 0 \Rightarrow \boldsymbol{E_1} = \boldsymbol{0}$$

2^{nd} case $r \ge R$

The Gauss surface is outside the sphere to calculate $E_2=E_{outs}$

$$dq = \sigma ds \Rightarrow Q_{int} = \sigma 4\pi R^2$$

So $E_2 4\pi r^2 = \frac{\sigma 4\pi R^2}{\varepsilon_0} \Rightarrow E_2 = \frac{\sigma R^2}{\varepsilon_0 r^2}$

- The electrostatic potential V(r) at any point in space.

$$\vec{E} = -\overrightarrow{grad}v \Rightarrow E = -\frac{dv}{dr}$$
 so $v = -\int Edr$

 $\underline{\mathbf{1}^{\text{st}} \operatorname{case} \mathbf{r} < \mathbf{R}} \qquad E_1 = \mathbf{0} \Rightarrow v_1 = C_1$

 $\underline{2^{\mathrm{nd}}\operatorname{case} \mathbf{r} \geq \mathbf{R}} \quad E_2 = \frac{\sigma R^2}{\varepsilon_0 r^2} \Rightarrow v_2 = -\sigma \frac{\sigma R^2}{\varepsilon_0} \int \frac{dr}{r^2} = \frac{\sigma R^2}{\varepsilon_0 r} + C_2$

Calculating constants :

- The potential at infinity is zero (v_w=0) so $\lim_{r\to\infty} v = 0$ so C₂=0 then $v_2 = \frac{\sigma R^2}{\varepsilon_0 r}$
- The potential is a continuous function in R so $v_1(R) = v_2(R)$

then $v_1 = C_1 = \frac{\sigma R^2}{\varepsilon_0 R}$ so $v_1 = \frac{\sigma R}{\varepsilon_0}$

- Plot the graphs E(r) and V(r) as a function of r :







b- Sphere charged in volume

1- The electrostatic field E(r) at any point in space.

We have 2 cases:

1st case r<R

$$dq = \rho dv = \rho 4\pi r^2 dr \Rightarrow Q_{int} = \rho \iiint dv = \rho 4\pi \int_0^r r^2 dr$$

We integrate between 0 and r because the Q_{int} charge is located in the volume of the Gauss sphere of radius r.

$$\Rightarrow Q_{int} = \rho \ \frac{4}{3}\pi r^3 \quad \text{so } (*) \Rightarrow E_1 = \frac{\rho \frac{4}{3}\pi r^3}{4\pi r^2 \varepsilon_0} \text{ then } E_1 = \frac{\rho}{3\varepsilon_0} r = E_{ins}$$

2^{nd} case $r \ge R$

$$dq = \rho dv = \rho 4\pi r^2 dr \Rightarrow Q_{int} = \rho \iiint dv = \rho 4\pi \int_0^R r^2 dr$$

We integrate between 0 and R because the Q_{int} charge is located in the volume of the sphere of radius R.

So $Q_{int} = \rho \frac{4}{3}\pi R^3$

$$(*) \Rightarrow E_2 = \frac{\rho \frac{4}{3}\pi R^3}{4\pi r^2 \varepsilon_0} \quad so \quad E_2 = \frac{\rho R^3}{3\varepsilon_0 r^2} = E_{out}$$

2- The electric potential v(r) at any point in space.

 $\vec{E} = -\overline{grad}v \Rightarrow E = -\frac{dv}{dr}$ So $v = -\int Edr$

1st case r<R:

$$E_1 = \frac{\rho}{3\varepsilon_0} r \Rightarrow v_1 = -\frac{\rho}{3\varepsilon_0} \int r dr$$
 so $v_1 = -\frac{\rho}{6\varepsilon_0} r^2 + C_1$

<u> 2^{nd} case $r \ge R$:</u>

$$E_2 = \frac{\rho R^3}{3\varepsilon_0 r^2} \Rightarrow v_2 = -\frac{\rho R^3}{3\varepsilon_0} \int \frac{1}{r^2} dr \text{ so } v_2 = \frac{\rho R^3}{3\varepsilon_0} \frac{1}{r} + C_2$$

Calculating constants :

Ms Hadjou Bélaid Z



The potential at infinity is zero (v_∞=0) so $\lim_{r\to\infty} v = 0$ then $v_2 = \frac{\rho R^3}{3\epsilon_0} \frac{1}{r}$

The potential is a continuous function in R, so $v_1(R) = v_2(R)$

$$\frac{\rho R^3}{3\varepsilon_0} \frac{1}{R} = -\frac{\rho}{6\varepsilon_0} R^2 + C_1 \Rightarrow C_1 = \frac{\rho R^2}{\varepsilon_0} \left(\frac{1}{3} + \frac{1}{6}\right) = \frac{\rho R^2}{2\varepsilon_0}$$

so
$$v_1 = -\frac{\rho r^2}{6\varepsilon_0} + \frac{\rho R^2}{2\varepsilon_0}$$

5.4. Case of an infinite plan

To find the electric field in an infinite plane,

we use Gauss's theorem.

The Gaussian surface is a cylinder intersecting the plane.

The cylinder has radius r and height h.

For reasons of symmetry, the field is radial and constant at any point on the Gaussian surface.

In the Gaussian surface.

$$\emptyset = \oint \vec{E} \cdot \vec{dS} = \frac{\sum Q_{int}}{\varepsilon_0}$$
$$\emptyset = \emptyset_{sbase1} + \emptyset_{slat} + \emptyset_{sbase2} = \iint \vec{E} \cdot \vec{dS_{B1}} + \iint \vec{E} \cdot \vec{dS_{B2}} + \iint \vec{E} \cdot \vec{dS_L}$$

$$= 2 \iint E. dS_{base} = 2E. S_{base}$$

$$\Rightarrow \phi = 2E.S_{base} = \frac{\Sigma Q_{int}}{\varepsilon_0}$$
(1)

$$dq = \sigma ds \Rightarrow Q_{int} = \sigma \iint ds = \sigma S_{base}$$

(1)
$$\Rightarrow 2E. S_{base} = \frac{\sigma S_{base}}{\varepsilon_0}$$
 so $E = \frac{\sigma}{2\varepsilon_0}$

Then $\lim_{R\to\infty} |E| = \frac{\sigma}{2\varepsilon_0}$ and the field for an infinite plane is identical.

