**CHAPTER 2** 

# **DIMENSIONING IN SIMPLE BENDING**

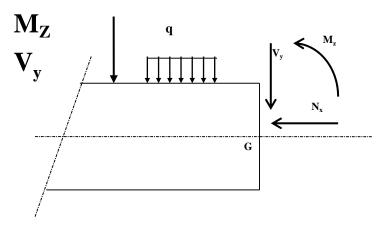
# Justifications for normal loads

## 1) Definition

A medium-plane beam is subject to simple plane bending if the loads are reduced to :F

- A bending moment :
- And a shear force :
- 2) Justifications

In reinforced concrete, a distinction is made between :



- The action of the bending moment which leads to the dimensioning of the longitudinal reinforcements.
- The action of the shear force, which concerns the design of the transverse reinforcement.
- These two calculations are carried out separately and in this section we will limited to the bending moment calculations.

### 3) Beam spans

In reinforced concrete, the span of the beams to be taken into account is :

- The span between support centres when there are support devices or when the beam rests on masonry walls,
- > The span between bare supports when the supports are in reinforced concrete ( principal beam, column or wall).

Justifications for bending moment

### Three limit states are to be considered for the justification of

#### deflected beams:

- ✓ Ultimate resistance limit state
- ✓ Service limit state with regards to durability
- ✓ Service limit state with regards to deformation

## *I. Ultimate Limit State of Resistance*

We need to check that:

# $M_u \leq M_{ur}$

Where:

**M**<sub>u</sub> : is the applied moment (design moment)

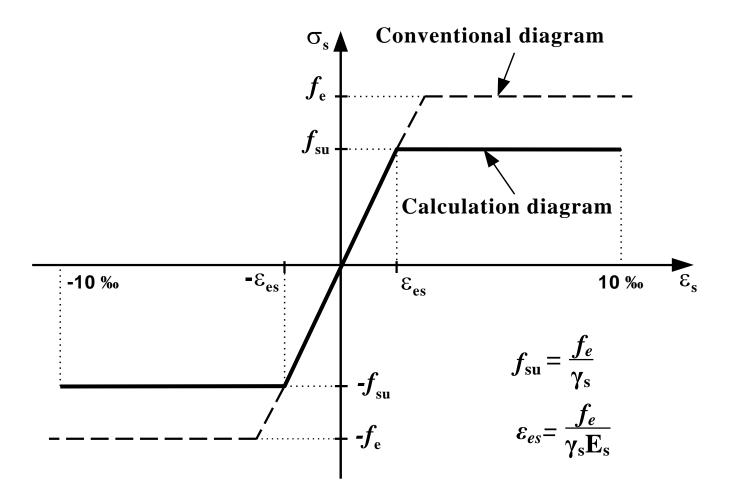
and  $M_{ur}$ : is the resisting moment of the section

## 1) Calculation hypotheses

The main assumptions for the ULS (ELU) design of the RC sections subjected to simple bending are as follows:

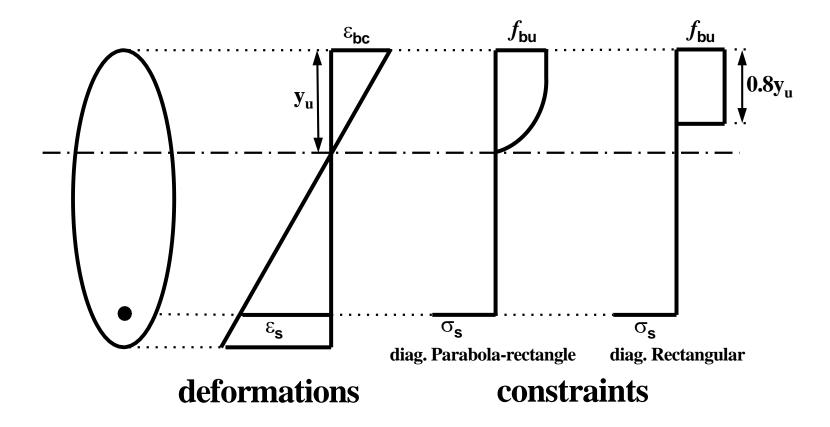
- > Straight sections remain flat after deformation (Navier-Bernoulli hypothesis),
- > There is no relative sliding between the reinforcement and the concrete, and the

tension in the concrete is neglected,



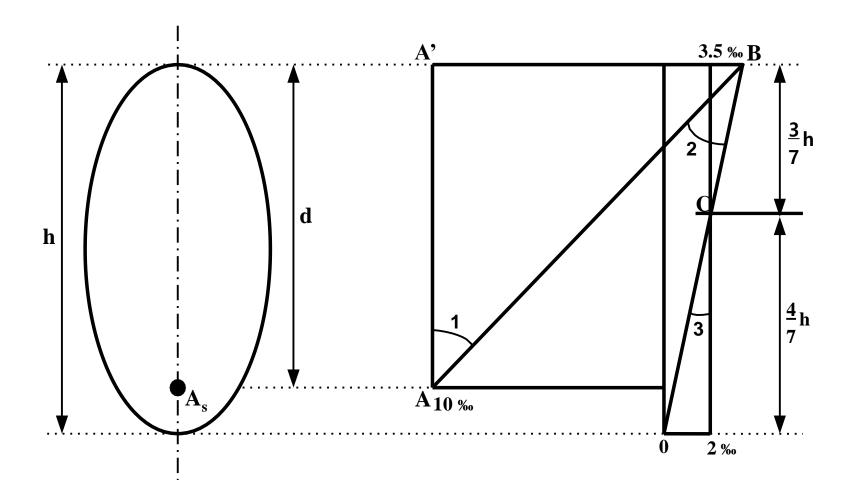
**Stress-strain diagram for steel calculations** 

f) for concrete >> simplified rectangular diagram (Article A.4.3,42).

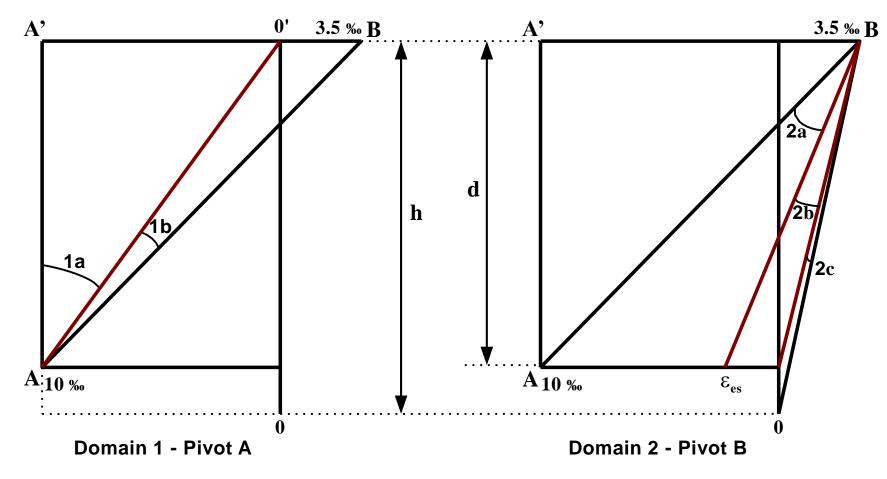


# g) $\epsilon_{\rm b} \leq 3.5\%$ in flexion et 2‰ in simple compression $\epsilon_{\rm s} \leq 10\%$

The deformation diagram of the section at E.L.U.R (Article A.4.3.3) therefore passes through one of the 3 pivots A, B or C defined below:

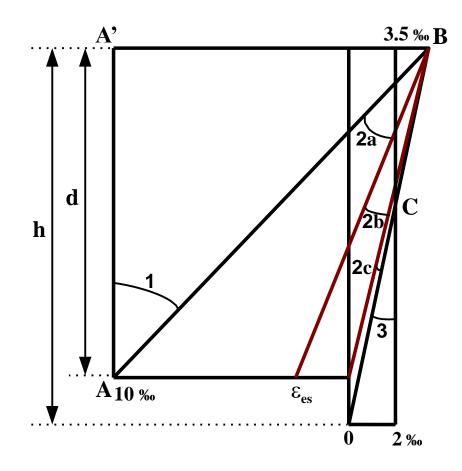


#### 2) Possible deformation lines for simple bending



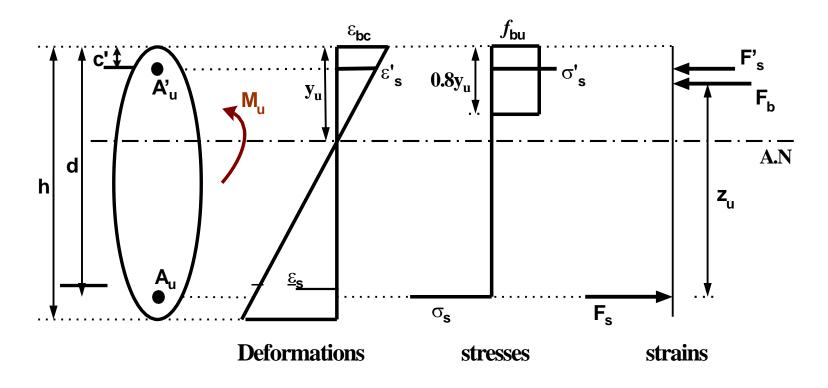
Let  $y_u$  be the depth of the neutral axis,

 $\alpha_u = y_u/d$  is the relative depth of the neutral axis Determine the bounds of  $\alpha_u$  for each domain.



domain 1 :	$\alpha_{\rm u} \leq 0.259$
domain 2a :	$0.259 < \alpha_u \leq \alpha_\ell$
with $\alpha_{\ell} =$	$=$ 3.5 / (3.5 + 1000 $\epsilon_{es}$ )
domain 2b :	$\alpha_{\ell} < \alpha_{u} \leq 1$
domain 2c :	$1 < \alpha_u \leq \alpha_{BC} = h/d$
domain 3 :	$h/d < \alpha_u$

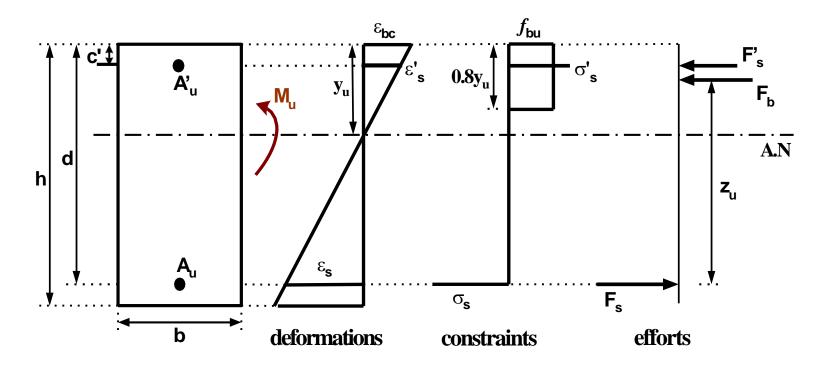
3) Notations - Equilibrium equations



The equilibrium of the section results in the following two equations:

- > Equilibrium of normal forces :  $F_b + F'_s F_s = 0$
- Equilibrium of moments in relation to the centre of gravity of the tensioned steel :  $F_b z_u + F'_s (d - c') = M_u$

4) Case of rectangular sections



In this case we have :

$$F_{b} = 0.8 b y_{u} f_{bu}$$

$$F_{s} = A_{u} \cdot \sigma_{s}$$

$$F'_{s} = A'_{u} \cdot \sigma'_{s}$$

$$z_{u} = d - 0.4 y_{u}$$

#### Moment résistant béton :

$$M_{b} = \mathbf{F}_{b} \mathbf{z}_{u} = \mathbf{0.8} \ b \ y_{u} f_{bu} \ (d - \mathbf{0.4} \ y_{u} \ )$$
  
=  $\mathbf{0.8} \ b. \ y_{u} / \mathbf{d} \ .f_{bu} \ .\mathbf{d}^{2} (\mathbf{1} - \mathbf{0.4} \ y_{u} / \mathbf{d})$   
=  $\mathbf{0.8} \alpha_{u} \ (\mathbf{1} - \mathbf{0.4} \alpha_{u}) \ \mathbf{bd}^{2} \ .f_{bu} \qquad avec \qquad \alpha_{u} = y_{u} / \mathbf{d}$ 

We can write:  $M_b = \mu_u \operatorname{bd}^2 f_{bu}$ with  $\mu_u = 0.8\alpha_u (1 - 0.4\alpha_u)$  et  $\alpha_u = y_u / d$ 

- $\mu_u$  is called the relative moment of the concrete or 'reduced ultimate moment'.
- $\alpha_u$  is the relative depth of the neutral axis
- > Equilibrium equations :  $0.8 \ a_u \ bdf_{bu} + A'_u \ \sigma'_s - A_u \ \sigma_s = 0$   $\mu_u \ bd^2 f_{bu} + A'_u \ \sigma'_s \ (d - c') = M_u$

What are the unknowns in this system of equations?

if the deformation diagram is known, the parameters  $y_u$ ,  $\varepsilon_{bc}$ ,  $\varepsilon_s$ ,  $\varepsilon'_s$ ,  $\sigma_s$  et  $\sigma'_s$  are known.

In fact : The deformation diagram gives:  $\frac{\overline{y_u}}{y_u} = \frac{\overline{d} - \overline{y_u}}{\overline{d} - \overline{y_u}} = \frac{\overline{d} - \overline{d}}{\overline{y_u} - \overline{d}}$ if the deformation line passes through the pivot A we have :  $\varepsilon_s = 10 \%_0; \quad \varepsilon_{bc} = \frac{y_u}{d - y_u} = \frac{10\%_0}{d - y_u} = \frac{y_u - c'}{d - y_u} = \frac{10\%_0}{d - y_u}$  $\frac{\varepsilon_{bc}}{y_u} \frac{\varepsilon_s}{d-y_u} = \frac{\varepsilon_s}{y_u-c'}$ d and if the deformation line passes through the pivot B we have :  $a_{x} = 35\%$ ;  $\epsilon_{s} = \frac{d - y_{u}}{v_{u}} 35\%$  et  $\epsilon'_{s} = \frac{y_{u} - c'}{v_{u}} 35\%$ 

Once the deformations are known, the corresponding stresses can be deduced.

Now let's assume that the dimensions of the section of concrete (b,h)are known

and take approximate values for d and c' to be d=0.9het c'=d/9

This leaves a number of unknowns:

the y<sub>u</sub> position of the deformation diagram
 and reinforcement sections A<sub>u</sub>, A'<sub>u</sub>

### <u>RO</u>

As the steel reinforcement is primarily intended to absorb the tensile stress, we will first assume that :  $A'_u = 0$ 

#### a) Section without compressed reinforcement

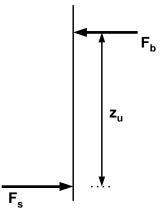
if  $A'_{u} = 0$  the equilibrium of the moments gives:

$$\mu_u = \frac{M_u}{\mathbf{b}\mathbf{d}^2 f_{bu}} \qquad (\mathbf{F}_{\mathbf{b}} \mathbf{z}_{\mathbf{u}} = \mathbf{M}_{\mathbf{u}})$$

or  $\mu_u = 0.8 \alpha_u (1 - 0.4 \alpha_u)$ 

So  $\alpha_u$  is the lower race of the equation:

0.4 
$$\alpha_{\rm u}^2 - \alpha_{\rm u} + 1.25 \mu_u = 0$$



soit  $\alpha_u = \frac{1 - \sqrt{1 - 2 \mu_u}}{0.8} = 1.25(1 - \sqrt{1 - 2 \mu_u})$ 

Writing the equilibrium of the moments with respect to the point of application of  $F_b$ , we obtain :

$$M_u = \mathbf{F}_{\mathbf{s}} \, \mathbf{z}_{\mathbf{u}} = A_u \, \boldsymbol{\sigma}_{\mathbf{s}} \, \mathbf{z}_{\mathbf{u}}$$

**Resulting :** 

$$A_{u} = \frac{M_{u}}{\sigma_{s} z_{u}} \text{ avec } z_{u} = d(1 - 0.4\alpha_{u}) \text{ et } \alpha_{u} = 1.25(1 - \sqrt{1 - 2\mu_{u}})$$

#### b) Position of the deformation diagram

To place the deformation diagram within the domain possible, possible, we compare the reduced moment of calculation  $\mu_u$ 

 $\mu_u = \frac{M_u}{\mathrm{bd}^2 f_{bu}}$ 

with the reduced moments corresponding to the limits of the different domains.

